

Stat 111 Spring 2011 Week 12 Problems - Objective Bayesian Inference

Bayesian inference is useful if you want to incorporate prior information into your analysis. But the most important argument for the Bayesian approach is that it provides a coherent strategy for making inference about any parametric problem: Write down a probability model for the data, specify prior distributions for the unknown parameters, then make inference based on the conditional (posterior) distributions of the parameters, given the data.

A common complaint about Bayesian inference is that different prior assumptions lead to different conclusions. *Objective Bayes* inference involves finding prior distributions that yield good frequentist properties (e.g., 90% interval estimates that cover the true parameter for 90% of data sets).

1. The average height for the 16 women who answered my Stat 1 survey this Spring is $\bar{y} = 65.0$ inches. Assume that this represents a simple random sample of all Swarthmore women, and that heights vary according to a Normal distribution. You wish to make inference about μ , the true mean height of all Swarthmore women. For now, assume we know that the standard deviation of Swarthmore women's heights is 3.0 inches.
 - a) Say you're "certain" that the mean height is between 60 and 70 inches, but you don't want to say any more than that. You could specify a Uniform prior density between 60 and 70 inches. Derive the posterior density for $f(\mu|\bar{y})$ and find a 90% "credible interval" for μ . Explain precisely what this interval represents.
 - b) For Bayesian inference, we may specify an improper prior density (i.e., a density that does not have a finite integral) as long as the corresponding posterior density is proper (i.e., has a finite integral). Show that a flat prior density on $-\infty$ to ∞ (i.e., $p(\mu) \propto c$) yields a proper posterior density in this problem, and compare it to the posterior density from part a. Improper prior densities do not present a paradox; rather, they are a mathematical convenience.
 - c) Previous surveys of Swarthmore students might lead me to specify a Normal prior density with mean $\mu_o = 64.5$ and standard deviation $\tau = 1$ (I could be more precise than that, but I don't want to be too subjective). Work out the posterior density for the general problem of estimating the mean μ of a Normal distribution, when assuming the prior distribution $p_\mu(\mu)$ that is $N(\mu_o, \tau^2)$.
2. The goal in Objective Bayesian inference is to specify a prior density that is "non-informative." Uniform prior distributions make all values of a parameter equally likely, but that doesn't necessarily equate to not injecting any prior information into the problem. If you specify a Uniform prior density for a parameter θ , then the implied prior density for any non-linear function $\phi = g(\theta)$ is not Uniform, so some values of ϕ are *a priori* more probable than others.

- a) What do we mean by a density function and a change of variables? Consider a random variable θ with density p_θ , and a transformation $\phi = g(\theta)$ with density p_ϕ . Find the relationship between these two densities by equating $P(\theta \in [\theta, \theta + d\theta]) = p_\theta(\theta)d\theta$, and $P(\phi \in [\phi, \phi + d\phi]) = p_\phi(\phi)d\phi$. This will involve finding a first order Taylor approximation to the function $g(\theta + d\theta)$ centered at θ . For example, let $\phi = \log(\theta)$.
- b) The **Jeffreys' prior density** for a parameter θ is the density implied by specifying a Uniform density on a particular transformation $\phi = g(\theta)$. The transformation $\phi = g(\theta)$ is chosen such that the Fisher information for ϕ is the same for all data sets of the same size, regardless of the value of ϕ . This is a scale where it makes sense to say “non-informative” means “all values of ϕ are equally likely.” Show this is the case for $\phi = \log(\sigma^2)$ for a sample from a $N(0, \sigma^2)$ distribution. Using the same axis, graph the log-likelihood function for σ^2 based on a sample of $n = 10$ with MLE $\hat{\sigma}^2 = 16$, and for a sample with $\hat{\sigma}^2 = 9$. Subtract off the maximum log-likelihood value so that both graphs have maximum value 0. Repeat this for $\phi = \log(\sigma^2)$. Notice that the curvature differs for the two σ^2 log-likelihoods, but not for the two ϕ log-likelihoods.
- c) A Uniform prior density for $\log(\sigma^2)$ implies a density $p_{\sigma^2}(\sigma^2)d\sigma^2 \propto d\sigma^2/\sigma^2$. A prior density that satisfies the requirements we applied here (specifying a Uniform prior density on a transformation of θ that has constant information) is called “Jeffreys' prior” (Lord Jeffreys once wrote: “It is sometimes considered a paradox that the answer depends not only on the observations but on the question; it should be a platitude.”) The problem simplifies to setting $p(\theta)$ proportional to the square root of the Fisher Information:

$$p(\theta) \propto \left(-E \left(\frac{\partial^2}{\partial^2 \theta} \log(L(\theta)) \right) \right)^{1/2}.$$

Find the Jeffreys' prior densities for the mean and variance of a Normal distribution.

- d) Multiply the prior densities from c) gives a non-informative joint prior distribution for μ and σ^2 . We have seen that this prior implies a $t_{(n-1)}$ marginal posterior density for $(\mu - \bar{y})/(s/\sqrt{n})$. It is often not possible to get a closed-form solution like this. An alternative way to characterize a posterior density f is to simulate a large number of random draws from f . Outline a 2-step algorithm for simulating from the joint posterior distribution of μ and σ^2 . Integrate μ out of the joint posterior distribution and recognize the resulting marginal posterior for $\sigma^2|y$, and the conditional posterior for $\mu|y, \sigma^2$. Explain how making sequential draws from these two distributions gives draws from the joint posterior, and that the sample of μ values represents draws from the marginal posterior density for $\mu|y$.

3. Consider the 2-level Normal hierarchical model with constant and known level-1 variance V :

$$\begin{aligned} Y_i | \theta_i &\stackrel{\text{indep}}{\sim} N(\theta_i, V), \quad i = 1, \dots, k. \\ \theta_i | \mu, A &\stackrel{\text{i.i.d.}}{\sim} N(\mu, A). \end{aligned}$$

For example, each Y_i might represent the average point total for a particular team in their first n games. Assuming the same standard deviation for all teams, we have $V = \sigma/n$, with σ estimated based on $k(n-1)$ degrees of freedom. If this value is large, then V is essentially known.

- a) It is well-established that a Uniform density on $(-\infty, \infty)$ is a reasonable non-informative prior density for the mean μ of a Normal random variable. Treating μ as known (for now) derive the Jeffreys prior density for $B = V/(V + A)$.
- b) If an independent Uniform prior distribution is assumed for μ , then your answer to (a) is the implicit joint-prior density for μ and B . Making this prior specification, find the marginal posterior density $f(B|Y)$ and show that the posterior mode for B (the value of B that maximizes its marginal posterior density) is the Stein estimate: $\hat{B} = \min\{1, (k-3)V/\sum((y_i - \bar{y})^2)\}$.
- c) Find the conditional posterior density for $\mu|y, B$ and for $\theta|y, B$. Use these to find the modified posterior standard deviation estimates for the θ_i 's described in the article *Stein's Paradox Revisited*.