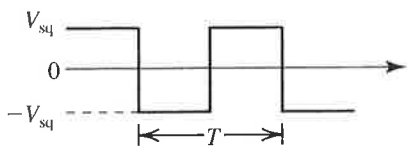




1.33 If the amplitude of the square wave is  $V_{sq}$  then the power delivered by the square wave to a resistance  $R$  will be  $V_{sq}^2 / R$ . If this power is to equal that delivered by a sine wave of peak amplitude  $\hat{V}$  then



$$\frac{V_{sq}^2}{R} = \frac{(\hat{V} / \sqrt{2})^2}{R}$$

Thus,  $V_{sq} = \hat{V} / \sqrt{2}$ . This result is independent of frequency.

1.34

Decimal	Binary
0	0
5	101
8	1000
25	11001
57	111001

1.35

$b_3$	$b_2$	$b_1$	$b_0$	Value Represented
0	0	0	0	+0
0	0	0	1	+1
0	0	1	0	+2
0	0	1	1	+3
0	1	0	0	+4
0	1	0	1	+5
0	1	1	0	+6
0	1	1	1	+7
1	0	0	0	-0
1	0	0	1	-1
1	0	1	0	-2
1	0	1	1	-3
1	1	0	0	-4
1	1	0	1	-5
1	1	1	0	-6
1	1	1	1	-7

Note that there are two possible representation of zero: 0000 and 1000. For a 0.5-V step size, analog signals in the range  $\pm 3.5$  V can be represented

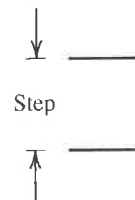
Input	Steps	Code
+2.5 V	+5	0101
-3.0 V	-6	1110
+2.7	+5	0101
-2.8	-6	1110

1.36 (a) For  $N$  bits there will be  $2^N$  possible levels, from 0 to  $V_{FS}$ . Thus there will be  $(2^N - 1)$  discrete steps from 0 to  $V_{FS}$  with the step size given by

$$\text{Step size} = \frac{V_{FS}}{2^N - 1}$$

This is the analog change corresponding to a change in the LSB. It is the value of the resolution of the ADC.

(b) The maximum error in conversion occurs when the analog signal value is at the middle of a step. Thus the maximum error is



$$\frac{1}{2} \times \text{step size} = \frac{1}{2} \frac{V_{FS}}{2^N - 1}$$

This is known as the quantization error.

(c)  $\frac{10 \text{ V}}{2^N - 1} \leq 5 \text{ mV}$

$$2^N - 1 \geq 2000$$

$$2^N \geq 2001 \Rightarrow N = 11,$$

For  $N = 11$

$$\text{Resolution} = \frac{10}{2^{11} - 1} = 4.9 \text{ mV}$$

$$\text{Quantization error} = \frac{4.9}{2} = 2.4 \text{ mV}$$

1.37 When  $b_i = 1$ , the  $i$ th switch is in position 1 and a current  $(V_{ref}/2^i R)$  flows to the output. Thus  $i_o$  will be the sum of all the currents corresponding to "1" bits, i.e.,

$$i_o = \frac{V_{ref}}{R} \left( \frac{b_1}{2^1} + \frac{b_2}{2^2} + \dots + \frac{b_N}{2^N} \right)$$

(b)  $b_n$  is the LSB  
 $b_1$  is the MSB

RESOLUTION OF ADC

$$3.3V/1024 = 3.22mV$$

TEMPERATURE RESOLUTION

$$VOLTAGE RESOLUTION = 1.5/1024 = 1.46mV$$

$$V_{TEMP} = .00355 (TEMP_C) + .986$$

$$TEMP_C = 281.69 V_{TEMP} + 277.7 \quad \text{IF } \Delta V = 1.46mV$$

$$\Delta T = 281.69 \cdot \Delta V = 0.4^\circ$$

pbFlag is volatile because, to compiler, it looks like it doesn't change, so it could be optimized away.

~~...~~

main.c

```
1 #include <msp430.h>
2
3 #define P1LED BIT0
4 #define P1SW BIT3
5 /* This program sets up P1.0 as an output (connected
6 * to an LED, and P1.3 as in input with a pull up
7 * resistor, connected to a switch.
8 * On the falling edge of P1.3 and interrupt is generated
9 * that raises a flag.
10 * In the main loop, if the flag is raised, the LED is toggled.
11 */
12 volatile int pbFlag=0;
13 #define LED BIT0
14
15 void main(void) {
16     WDTCTL = WDTPW + WDTHOLD; // Stop watchdog
17
18     P1OUT &= ~P1LED;           // Turn LED off.
19     P1DIR |= P1LED;           // Make LED an output
20
21     P1REN |= P1SW;            // Add resistor to switch
22     P1OUT |= P1SW;            // Make it a pull-up resistor.
23     P1IES |= P1SW;            // Make interrupt falling edge.
24     P1IE  |= P1SW;            // Enable interrupt on switch.
25     P1IFG &= ~P1SW;          // Clear interrupt flag.
26
27     __bis_SR_register(GIE);   // enable interrupts globally
28
29     while (1){
30         if (pbFlag) {
31             pbFlag = 0;
32             P1OUT ^= LED;
33         }
34     }
35 }
36
37 // Port 1 interrupt service routine
38 #pragma vector=PORT1_VECTOR
39 __interrupt void Port_1(void) {
40     pbFlag = 1;                // Set flag to signal interrupt.
41     P1IFG &= ~P1SW;           // Clear interrupt flag.
42 }
43
44
```